

1 Reconnection Dynamics with Secondary Tearing Instability in 2 Compressible Hall Plasmas

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6
7 **Abstract:** The dynamics of a secondary tearing instability is systematically
8 investigated based on compressible Hall MHD. It is found that in the early nonlinear
9 phase of magnetic reconnection before onset of the secondary tearing instability, the
10 geometry of the magnetic field in the reconnection region tends to form a Y-type
11 structure in a weak Hall regime, instead of an X-type structure in a strong Hall regime.
12 A new scaling law is found that the maximum reconnection rate in the early nonlinear
13 stage is proportional to the square of the ion inertial length ($\gamma \propto d_i^2$) in the weak Hall
14 regime. In the late nonlinear phase, the thin elongated current sheet associated with
15 the Y-type geometry of the magnetic field breaks up to form a magnetic island due to
16 a secondary tearing instability. After the onset of the secondary tearing mode, the
17 reconnection rate are substantially boosted by the formation of the X-type geometries
18 of magnetic field in the reconnection regions. With a strong Hall effect, the maximum
19 reconnection rate linearly increases with the increase of the ion inertial length
20 ($\gamma \propto d_i$).

21
22 **Keywords:** Magnetic reconnection, tearing instability, secondary tearing mode, Hall
23 MHD

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28 1. Introduction

29 Magnetic reconnection is an effective mechanism to convert magnetic energy to
30 kinetic and thermal energies and also leads to exchange of mass, momentum, energy
31 between the two sides of the central current sheet. Magnetic reconnection is often
32 cited as an efficient mechanism for many eruptive physical phenomena such as flares
33 in the solar corona, substorms in the Earth's magnetosphere, and sawtooth oscillations
34 in Tokamaks [Sweet, 1958; Parker, 1963; Yamada *et al.*, 2010; Biskamp, 2000]. In
35 order to use magnetic reconnection to explain observational phenomena [e.g. Nagai *et*
36 *al.*, 2012; Xiao *et al.*, 2007; Kopp and Pneuman, 1976], the time scale of magnetic
37 reconnection becomes a crucial issue, i.e., the reconnection time scale must be much
38 faster than the diffusion time scale.

39 The first well known steady state models of reconnection, the Sweet-Parker
40 model [Sweet, 1958; Parker 1957], states that the geometry of the reconnection layer
41 has a Y-type structure [Syrovatskii, 1971] and its length is of the order of the system
42 size. For high-S plasmas, however, the reconnection time scale
43 $\tau_{sp} = (\tau_A \tau_R)^{1/2} = S^{1/2} \tau_A$ for Sweet-Parker model is too long to explain fast
44 reconnection phenomena such as solar flare. The Petschek model [Petschek, 1964]
45 replaces by an X-type structure from the Y-type geometry in the Sweet-Parker model
46 and gives much faster reconnection time scale. Nevertheless, this model is not
47 realizable in high-S plasmas, unless the resistivity is locally and strongly enhanced at
48 the X-point. In the absence of such anomalous enhancement, the reconnection layer
49 evolves dynamically to form Y-points and realize a Sweet-Parker regime [Ma *et al.*,
50 1995].

51 In the reality, reconnection process, in general, is not steady-state, such as
52 sawtooth oscillations in Tokamaks, magnetospheric substorms and solar flares.
53 Magnetic reconnection is usually driven by external forces. Dynamic process of
54 externally driven magnetic reconnection, which is characterized by the formation of
55 near-singular current sheets in a finite time, exhibits a sudden change of the
56 reconnection rate after the magnetic configuration evolves slowly for a long period of

57 time. Analytical and simulation results based on the resistive magnetohydrodynamic
58 (MHD) model have already been obtained [Wang et al., 1996].

59 In high-S plasmas, when the width of the thin current sheet (Δ_η) satisfies
60 $c/\omega_{pe} \ll \Delta_\eta \ll c/\omega_{pi}$ (or $\sqrt{\beta}c/\omega_{pi}$ if there is a guide field), “collisionless” terms in
61 the generalized Ohm’s law cannot be ignored, which forms the so-called Hall MHD
62 Model. A scaling analysis of the forced reconnection within the framework of the Hall
63 MHD has been given by Wang et al. [2001]. This scaling law was confirmed by a later
64 work [Wang et al., 2006]. In the regime with weak Hall effects, a so-called secondary
65 tearing mode rises up, which has been presented by Zhang and Ma [2009] in their
66 double tearing investigation. Also, a scaling law, which describes the relationship
67 between the Lundquist number and the reconnection rate for the most rapidly growing
68 plasmoid instability, has been obtained by Bhattacharjee et al. [2009]. And several
69 subsequent works investigated more deeply on plasmoid scaling [e.g. Huang and
70 Bhattacharjee, 2010; Huang et al., 2013].

71 In this paper, we will quantitatively examine the formation and evolution process
72 of secondary tearing mode with different initial profile of magnetic field and plasma
73 density. Similar initial profile has already been used in the Ma and Feng’s work [2008]
74 that mainly focused on the generation of Hall electric field and net charge associated
75 with magnetic reconnection under the fixed ion inertial length. The time scales of the
76 maximum reconnection rates associated with the secondary tearing mode will present
77 under different initial profiles of the magnetic field and plasma density. A new scaling
78 law is found that the maximum reconnection rate before the onset of the secondary
79 tearing instability is proportional to the square of the ion inertial length, i.e., $\gamma \propto d_i^2$.
80 However, it should be noted the geometry of the reconnection region remains a Y-type
81 structure as in the Sweet-Parker mode even if the Hall effect still have a crucial
82 influence on the reconnection rate at the low level.

83 The layout of this paper is given as follows. In Section 2, Hall MHD equations
84 and numerical model are presented. Section 3 gives Hall MHD simulation results
85 from symmetric magnetic field and uniform plasma density, while Section 4 provides

86 several cases with asymmetric magnetic field or non-uniform plasma density profiles.
 87 Summary and discussion are placed in Section 5.

88

89 2. Equations and Numerical Model

90 The compressible Hall MHD model is employed to investigate the tearing mode
 91 dynamics in the process of magnetic reconnection. Resistivity is assumed to be
 92 uniform. Our simulations are conducted in the Cartesian coordinate system. The
 93 variation of all variables in the y-direction is assumed to be ignored; that is $\partial/\partial y = 0$

94 for all the time. The magnetic field is given with the form $\mathbf{B} = \hat{y} \times \nabla \psi + B_y \mathbf{y}$. The

95 compressible Hall MHD equations employed in our simulations are as follows

$$96 \quad \frac{\partial \rho}{\partial t} = -\nabla \cdot (\rho \mathbf{v}) \quad (1)$$

$$97 \quad \frac{\partial (\rho \mathbf{v})}{\partial t} = -\nabla \cdot [\rho \mathbf{v} \mathbf{v} + (p + B^2/2) \mathbf{I} - \mathbf{B} \mathbf{B}] \quad (2)$$

$$98 \quad \frac{\partial \psi}{\partial t} = -\mathbf{v} \cdot \nabla \psi + J_y / S + d_i (\mathbf{J} \times \mathbf{B})_y / \rho \quad (3)$$

$$99 \quad \frac{\partial B_y}{\partial t} = -\nabla \cdot (B_y \mathbf{v}) + \mathbf{B} \cdot \nabla v_y + \nabla^2 B_y / S$$

$$100 \quad -d_i \{ \nabla \times [(\mathbf{J} \times \mathbf{B} - \nabla p) / \rho] \}_y \quad (4)$$

$$101 \quad \frac{\partial p}{\partial t} = -\nabla \cdot (p \mathbf{v}) - (\gamma - 1) p \nabla \cdot \mathbf{v} + J^2 / S \quad (5)$$

102 where \mathbf{v} , \mathbf{B} , \mathbf{J} , ψ , ρ , p , \mathbf{I} are plasma velocity, magnetic field, current density, flux

103 function, plasma density, thermal pressure, and unit tensor, respectively. $\gamma (= 5/3)$ is

104 the ratio of specific heats of plasma. All variables are normalized as follows:

105 $\mathbf{B} / B_0 \rightarrow \mathbf{B}$, $\mathbf{x} / a \rightarrow \mathbf{x}$, $t / \tau_A \rightarrow t$, $v / v_A \rightarrow v$, $\psi / (B_0 a) \rightarrow \psi$, $\rho / \rho_0 \rightarrow \rho$,

106 $p / (B_0^2 / 4\pi) \rightarrow p$, where $\tau_A = a / v_A$ is the Alfvénic time, $v_A = B_0 / (4\pi\rho)^{1/2}$ is the

107 Alfvénic speed, $a = \lambda_B$ and λ_B is the half width of initial current sheet. $S = \tau_R / \tau_A$

108 is the Lundquist number, where $\tau_R = 4\pi a^2 / \eta c^2$, c is the speed of light, η is the

109 resistivity. d_i is the ion inertial length. The value of d_i can be used to represent the

110 intensity of the Hall effects.

111 Equations above are solved with fourth-order Runge-Kutta method in time and
112 fourth-order finite difference method in space. System size is chosen as $L_x = [-32, 32]$,
113 $L_z = [-16, 16]$, with 401×501 grid points which are nonuniform in both the x and z
114 directions. Period boundary condition is imposed at $x = \pm L_x$ and free boundary
115 condition, i.e., $\partial / \partial z = 0$ for all variables, is used at $z = \pm L_z$. The initial equilibrium
116 is force-balanced. Thermal pressure is obtained by solving equilibrium equation:

$$117 \quad p = (1 + \beta)B_0^2 / 2 - B^2 / 2 \quad (6)$$

118 where β is the asymptotic plasma beta. Initial magnetic field is given as:

$$119 \quad \mathbf{B} = (-B_1 + B_0 \tanh(z / \lambda_B)) \hat{x} \quad (7)$$

120 where λ_B is the half thickness of the current sheet, and is set to be 1.0 as a constant.

121 B_0 is the initial asymptotic magnetic field strength, offset by $-B_1$, which is used to
122 introduce asymmetric magnetic field. Other components of magnetic field are chosen
123 to be zero at the initial state; that is $B_y = B_z = 0$. Initial plasma velocity is set to be
124 zero, i.e. $v_x = v_y = v_z = 0$. In the present paper, we set $S = 1000$ for all cases.

125 The tearing mode is initially triggered by a small magnetic perturbation given by

$$126 \quad \delta\psi = \delta\psi_0 \cos(\pi x / L_x) \cos(\pi z / 2L_z) \quad (9)$$

127 where $\delta\psi_0 = 0.25$, which is chosen relatively large so that the system can attain a
128 fast magnetic reconnection process [Ma and Bhattacharjee, 2001].

129

130 **3. Simulation results with symmetric magnetic field and uniform plasma** 131 **density**

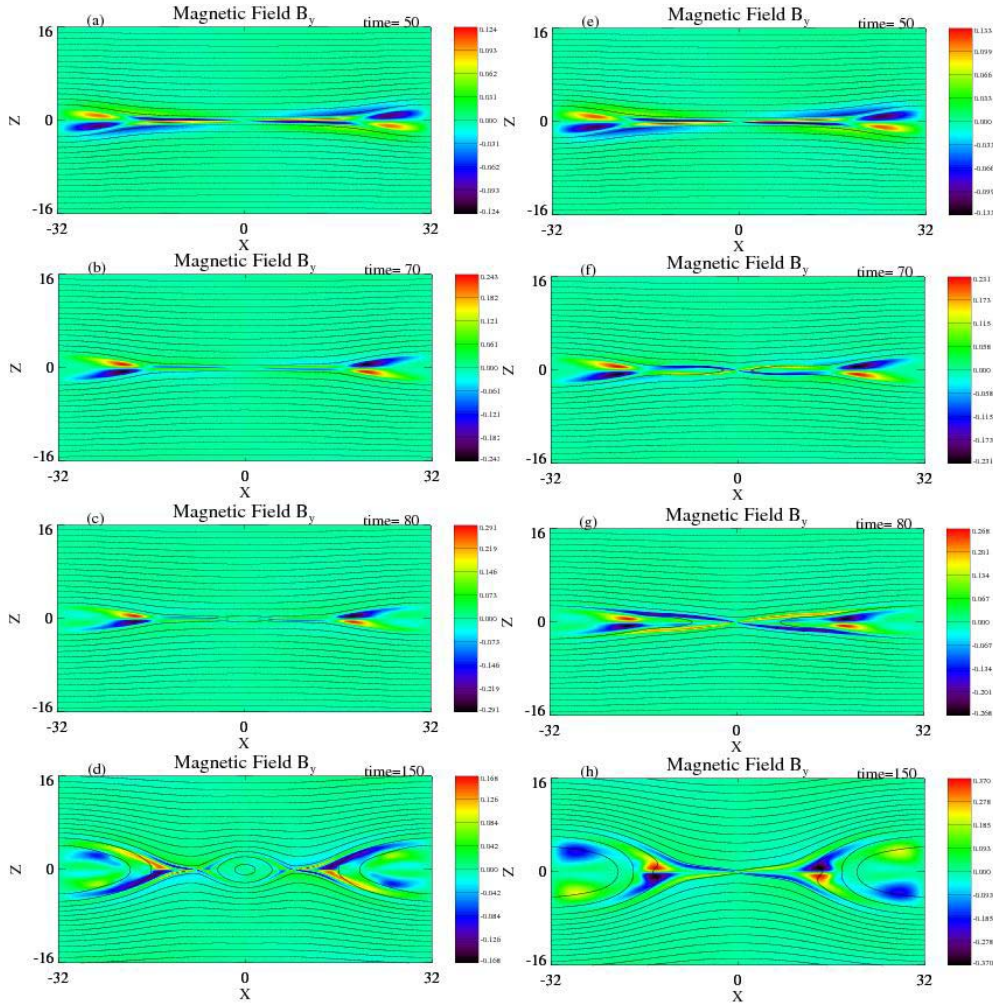
132 In our simulation, the magnetic reconnection rate γ can be calculated using the
133 following method [Ma and Bhattacharjee, 2001]:

134
$$\gamma = \frac{\partial}{\partial t} \psi_r(t) \quad (10)$$

135 where the flux function ψ_r is collected at the reconnection point .

136 In this section, we choose symmetric plasma density and magnetic field condition,

137 i.e., $B_0 = 1.0$, $B_1 = 0$ and the constant plasma density $\rho = 1.5$.



138

139 Figure 1. Contour images of B_y with magnetic field lines for $d_i = 0.5$ (left column)

140 and $d_i = 0.6$ (right column) at $t=50, 70, 80, 150$.

141

142 Figure 1 shows several snapshots of the contour image plots of the guiding field

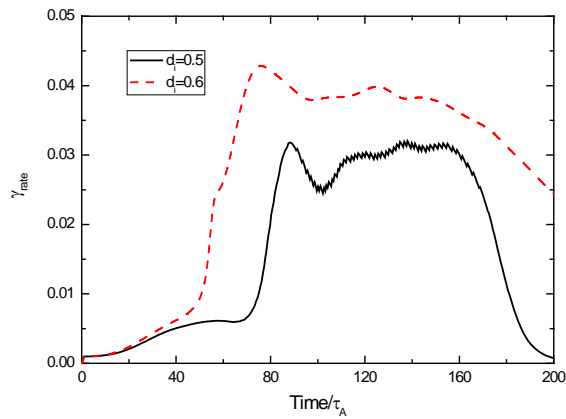
143 component B_y with magnetic field lines for the cases $d_i = 0.5$ and $d_i = 0.6$. It is

144 clearly shown that in the early phase of the magnetic reconnection, the geometry of

145 magnetic field as well as the magnitudes and structures of the guiding field B_y are

146 quite similar for the two cases as shown in Figures 1a and 1e because the Hall effect

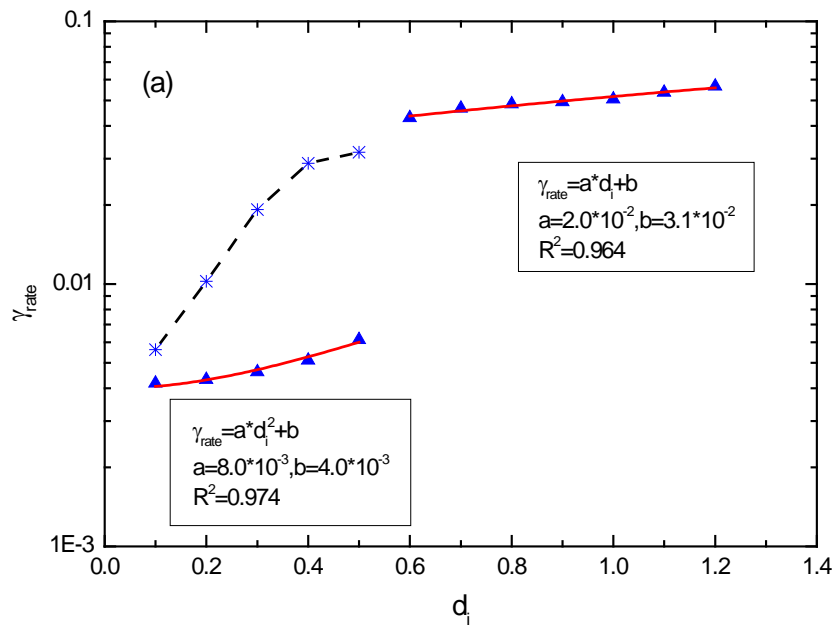
147 can be ignorable. After that, the reconnection dynamics of the two cases exhibit quite
 148 different scenarios. For the smaller d_i case, the reconnection region becomes further
 149 thin and elongated, and form a Y-type structure (Figure 1b). At the late stage $t=80$, the
 150 thin elongated current sheet breaks-up to form a magnetic island due to the secondary
 151 tearing instability (Figure 1c). The magnetic island further grows to a larger size
 152 (Figure 1d). For the larger d_i case, the reconnection region shrinks to form an X-type
 153 structure (Figure 1f). This X-type structure remains unchanged until the end of the
 154 simulation. There is no secondary tearing mode observed for the larger d_i case.



155
 156 Figure 2. The time evolutions of the reconnection rates for $d_i = 0.5$ (the solid line)
 157 and $d_i = 0.6$ (the dashed line).

158
 159 From the geometries of the magnetic field in Figure 1, we can separate the whole
 160 reconnection process into the reconnection stages before and after the onset of the
 161 secondary tearing instability for the smaller d_i regime. It is believed that there are
 162 double peaks of the reconnection rate associated with two different reconnection
 163 stages for the smaller d_i regime while there is only single peak of the reconnection
 164 rate for the larger d_i regime. The time evolutions of the reconnection rates are shown
 165 in Figure 2. Indeed, there exist two different reconnection stages for the smaller d_i
 166 regime. In the first stage, the thickness of the reconnection layer is not thin enough so
 167 that the reconnection dynamics are not mainly controlled by the Hall effect. After the
 168 onset of the secondary tearing instability, the Hall term in the generalized Ohm's law
 169 gradually becomes very important and the two reconnection regions exhibit the

170 X-type structure. Therefore, it is why the reconnection rate shows a bursty
 171 enhancement after the onset of the secondary tearing instability for the weak Hall
 172 regime. The reconnection rate in the second peak, resulted from the secondary tearing
 173 instability, increases more than five times of the reconnection rate in the first peak.
 174 The enhancement of the reconnection rate is rather lower in this Hall MHD model
 175 than in the resistive MHD model with a high Lundquist number [Bhattacharjee et al.;
 176 2009]. They found that the averaged reconnection rate associated with the onset of the
 177 secondary tearing instability exceeds the Sweet-Parker rate by nearly an order of
 178 magnitude after the onset of secondary tearing mode. The main reason for the weakly
 179 boosting effect of the reconnection rate in the Hall MHD model is that we have a
 180 higher reconnection rate resulted from weak contribution of the Hall effect in the first
 181 stage for the small d_i .



182
 183 Figure 3. Summary of all peak reconnection rates for different d_i . The symbols
 184 "triangular" and "star" indicate the peak reconnection rates before and after the onset
 185 of secondary tearing instability.

186
 187 Figure 3 shows the summary of all peak reconnection rates for different d_i . The
 188 peaks of the reconnection rates in the period with only one reconnection point existed

189 in the simulation domain appear a large jump between the small and large d_i regimes
190 as indicated by the solid lines. The critical value of d_i for the large jump of the
191 reconnection rate is in between 0.5 and 0.6. Therefore, it could be argued that strong
192 Hall effects for $d_i > 0.6$ in our model will lead to fast magnetic reconnection due to
193 an X-type reconnection geometry without other secondary effects. For $d_i < 0.6$, fast
194 magnetic reconnection can be achieved only through combination with the onset of
195 the secondary tearing instability.

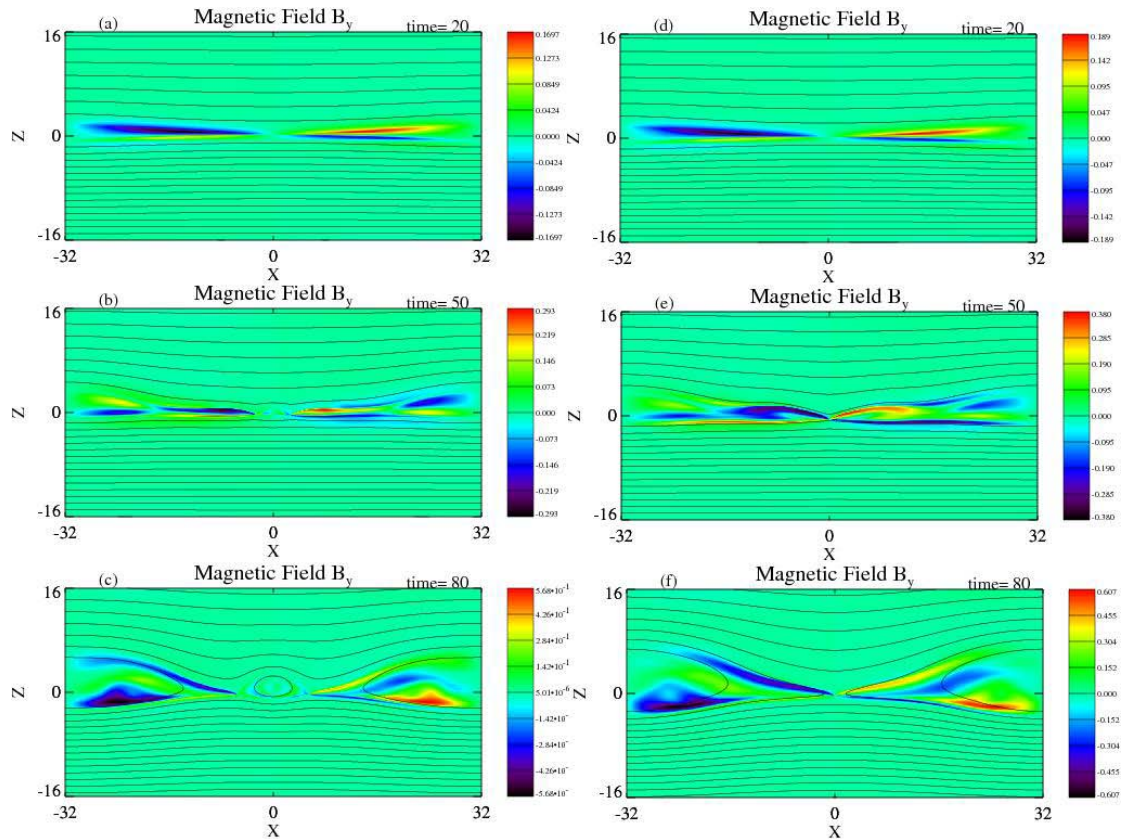
196 In order to examine the scaling law between the peak reconnection rate and the ion
197 inertial length, the best fitting lines (the solid lines) are also given in Figure 3. For the
198 small d_i regime, it is indicated that the first peak maximum reconnection rate before
199 the onset of the secondary tearing instability is proportional to the square of the ion
200 inertial length, i.e., $\gamma \propto d_i^2$. It is suggested that in the first stage, the Hall effect still
201 have a crucial influence on the reconnection rate at the low level even if the geometry
202 of the reconnection region exhibits a Y-type structure as in the Sweet-Parker mode.
203 After the onset of the secondary tearing mode, the reconnection rate rises up
204 dramatically, which is quite similar with the results from the resistive MHD model
205 with a high Lundquist number [Bhattacharjee et al., 2009]. Although the onset of the
206 secondary tearing mode causes much higher reconnection rate, the maximum
207 reconnection rate in this phase still lies below that for the cases with a large d_i . For
208 the cases with the large d_i , the maximum reconnection rate increases linearly as the
209 ion inertial length increases, which shows a nice straight line fitting, i.e., $\gamma \propto d_i$.

210

211 **4. Hall MHD simulation with asymmetric magnetic field or non-uniform** 212 **plasma density**

213 In the section, we investigate whether reconnection dynamics are affected by
214 non-uniform density or asymmetric magnetic field. First, we consider the cases with
215 the uniform plasma density and asymmetric magnetic field, i.e., $\rho = 1.5$ and
216 $B_x(z) = -0.5 + 1.5 \tanh(z)$. Figure 4 shows several snapshots of the contour image
217 plots of the guiding field component B_y with magnetic field lines for the cases

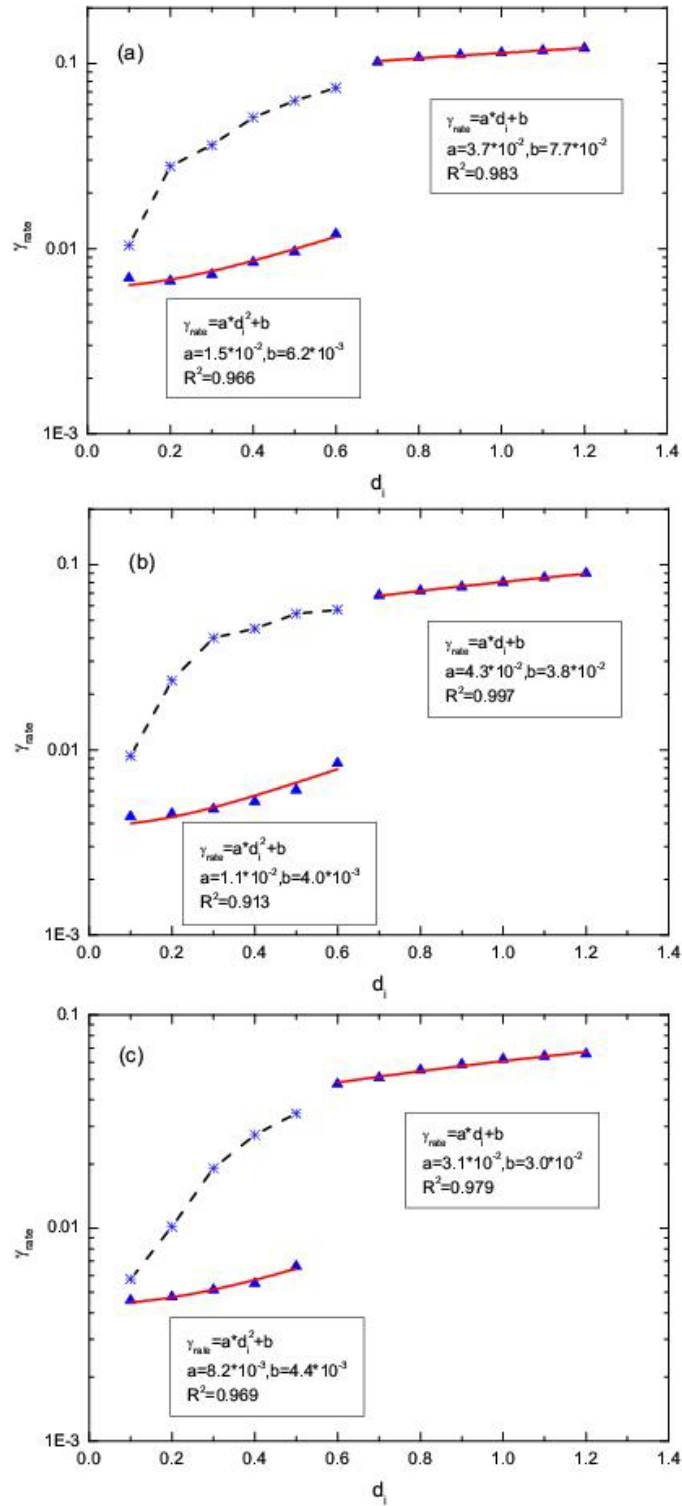
218 $d_i = 0.6$ and $d_i = 0.7$. In the early phase of the magnetic reconnection, the
 219 geometry of magnetic field as well as the magnitudes and structures of the guiding
 220 field B_y are quite similar for the two cases as shown in Figures 4a and 4d. The
 221 asymmetric magnetic field leads to breaking-up the quadrupole symmetry of the
 222 guiding fields which are much larger in the weak field side than the strong field side.
 223 At time=50, the reconnection dynamics exhibit quite different. the thin elongated
 224 current sheet associated with the Y-type geometry of the magnetic field breaks-up to
 225 form a magnetic island due to the onset of the secondary tearing instability (Figure
 226 4b). The magnetic island continuously grows to a larger size (Figure 4c). For the
 227 larger d_i case, the reconnection region shrinks to form an X-type structure (Figure
 228 4e). This X-type structure remains unchanged until the end of the simulation (Figure
 229 4f). There is also no secondary tearing mode observed for the larger d_i case. The
 230 guiding field exhibits a strong asymmetric and complicated distribution.



231

232 Figure 4. Contour image of B_y with magnetic field lines for $d_i = 0.6$ (left column)
 233 and $d_i = 0.7$ (right column) at $t=20, 50, 80$.

234



235

236 Figure 5. Dependence of peak reconnection rates on the ion inertial lengths d_i for
 237 three different initial profiles of the magnetic field and the plasma density. The
 238 symbols "triangular" and "star" indicate the peak reconnection rates before and after
 239 the onset of the secondary tearing instability.

240

241 Figure 5 shows the dependence of peak reconnection rates on the ion inertial
 242 lengths d_i for three different initial profiles of the magnetic field and the plasma
 243 density (a) $\rho = 1.5$ and $B_x(z) = -0.5 + 1.5 \tanh(z)$, (b) $\rho = 0.8 + 0.7/\cosh^2(z)$
 244 and $B_x(z) = \tanh(z)$, and (c) $\rho = 1.5 + 0.7 \tanh(z)$ and $B_x(z) = \tanh(z)$. For all
 245 three different initial profiles, the peaks of the reconnection rates in the first stage also
 246 exist large jumps between the small and large d_i regimes as indicated by the solid
 247 lines. The critical values of d_i for the large jump of the reconnection rate only have
 248 slight differences. For the small d_i regime, magnetic reconnection is boosted due to
 249 the onset of the secondary tearing instability. The different initial profiles of the
 250 magnetic field and plasma density give the same scaling law between the peak
 251 reconnection rate and the ion inertial length indicated by the best fitting lines (the
 252 solid lines) in Figure 5. For the small d_i regime, the first peak maximum
 253 reconnection rate before the onset of the secondary tearing instability is proportional
 254 to the square of the ion inertial length, i.e., $\gamma \propto d_i^2$. For the large d_i , the maximum
 255 reconnection rate increases linearly as the ion inertial length increases, i.e., $\gamma \propto d_i$.

256

257 5. Summary and Discussions

258 Spontaneous reconnection dynamics with different initial profiles of the magnetic
 259 field and the plasma density are systematically investigated using compressible Hall
 260 MHD model. It is found that in the weak Hall regime, the whole reconnection process
 261 can be separated into the reconnection stages before and after the onset of the
 262 secondary tearing instability. In the first stage, both the Hall term and the resistive
 263 term in the generalized Ohm's law control the reconnection dynamics. A new scaling
 264 law is found that the maximum reconnection rate before the onset of the secondary
 265 tearing instability is proportional to the square of the ion inertial length, i.e., $\gamma \propto d_i^2$.
 266 However, it should be noted the geometry of the reconnection region remains a Y-type
 267 structure as in the Sweet-Parker mode even if the Hall effect still have a crucial
 268 influence on the reconnection rate at the low level. After the onset of the secondary
 269 tearing instability, the Hall term in the generalized Ohm's law gradually becomes very

270 important and the geometries of the two reconnection regions exhibit the X-type
271 structure, which suggests that the dynamics of magnetic reconnection is fully
272 controlled by the Hall effect and the thickness of the reconnection layer goes well
273 down below the ion inertial length. The reconnection rate shows a bursty
274 enhancement for the weak Hall regime. The second maximum reconnection rate
275 triggered by the secondary tearing instability increases more than five times of the
276 first maximum reconnection rate. There is no obvious scaling law for the second
277 maximum reconnection rate.

278 With a strong Hall regime, the maximum reconnection rate linearly increases with
279 the increase of the ion inertial length, i.e., $\gamma \propto d_i$, which is different from the scaling
280 law $\gamma \propto d_i^{1/2}$ for the driving reconnection [Wang et al., 2001].

281

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