1	Effective Resistivity in Collisionless Magnetic Reconnection
2	Z. W. Ma^{1*} and T. Chen ¹
3	¹ Institute for Fusion Theory and Simulation, Department of Physics, Zhejiang University,
4	Hangzhou 310027, China.
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6	Abstract: Fast magnetic reconnection (FMR) in collisionless plasma is often attributed to the
7	off-diagonal electron Reynolds stress, which can give rise to a large induction electric field in the
8	reconnection region. However, in MHD simulations of FMR, it is difficult to implement the full
9	Reynolds stress, which is kinetic in nature. In this paper, an effective, or pseudo, resistivity, which
10	only accounts for the kinetic effects relevant to FMR, is introduced through the relation between
11	the electric field and the current density to investigate FMR. Justification of our approach is
12	vermed by run particle-in-cen simulations, and the corresponding physics is discussed.
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15	Keywords: Magnetic reconnection, Effective-resistivity, Collisionless plasma, PIC simulation
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23	*) Corresponding author: zwma@ziu.edu.cn
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27 **1. Introduction**

Magnetic reconnection (MR) is an important plasma process that efficiently converts magnetic energy into plasma kinetic and thermal energies [1, 2] and is believed to play crucial roles in the evolution of the solar corona [3-5], geomagnetic tail [6-8], magnetosphere [9, 10], as well as laboratory fusion plasmas [11, 12].

32 In collisionless plasma, a widely accepted physical mechanism for fast MR (FMR) is an 33 increase of the effect of the off-diagonal (with respect to the ambient magnetic field) electron 34 Reynolds stress in the diffusion region, which gives rise to a large reconnection electric field that 35 strongly accelerates the charged particles in the region [13, 14]. However, the Reynolds stress is 36 associated with the electron kinetic effects and can therefore not be easily implemented in fluid 37 descriptions of the plasma. In many MHD models, FMR is attributed to anomalous resistivity 38 arising from current-instability driven turbulence in the diffusion region [15, 16]. However, such 39 an anomalous resistivity often involves artificially given (usually constant) turbulence level or is 40 only current dependent. Speiser [17] introduced an effective conductivity for studying 41 collisionless FMR without invoking turbulence. However, the model does not include the details 42 of the particle motion that give rise to the effective conductivity, so that it is not clear how particles 43 are accelerated.

In this paper, we introduce an effective, or pseudo resistivity for considering collisionless FMR. The PR is obtained by replacing the collision mean-free-time in the traditional collisional drag force with the transit time of electrons in the small diffusion region around the X point of the MR. The transit time is obtained by following the motion of test electrons in the region and, as to be expected, is space and time dependent. Validity of our ad hoc model is confirmed by full particle-in-cell (PIC) simulation.

The rest of this paper is as follows. Section 2 presents our effective resistivity model and its properties. A theoretical argument justifying the effective resistivity is also given. Section 3 presents the corresponding PIC simulation. Section 4 compares the results from the model and the simulation. Section 5 gives a summary of our work.

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55 2. Physical Mechanisms and Model Description

56 Classically, plasma resistivity arises from inter-particle collisions that lead to momentum and 57 energy exchange between the colliding particles. It therefore depends on the collision frequency or the mean free path. In collisionless MR, particles in the small diffusion region around the X point experience strong electric and magnetic forces. A particle is first decelerated, and then accelerated as it enters and leaves the diffusion point due to the bent magnetic fields and the induction electric fields. It thereby exchanges energy with the fields. The interaction can thus lead to a local effective resistivity around the X point in a region of the order of the electron inertial length. The scenario is roughly similar to what occurs in a binary collision, namely the interaction takes place in a very small region around the center of mass or a massive particle, analogous to the X point in MR.

We consider the dynamics of a charge particle along an X line (assumed to be in the *z* direction, perpendicular to the MR plane) of the diffusion region, where the magnetic field is nearly zero and the induction electric field E_z is strong. The change in the velocity of the particle can be written as [17]

$$\delta v_z = q E_z \delta t / m, \qquad (1)$$

where q and m are the particle charge and mass, respectively, and δt is the transit time of the particle. Accounting for all the particles in the diffusion region, the corresponding change in the local current density is

73
$$\delta J_z = nq \delta v_z = nq^2 E_z \delta t / m, \qquad (2)$$

74 where n is the local particle density. Thus, one can define an effective resistivity

75
$$\eta \equiv E_{z} / J_{z} = m / nq^{2} \delta t, \qquad (3)$$

which is valid only near the X point. One must however still determine the particle density and thetransit time.

To model the diffusion region in collisionless MR, we consider a two-dimensional (2D) plane (x, y) with the X line lying in the perpendicular, or z, direction at (0,0). The vacuum magnetic and electric fields in this region can be approximated by

81
$$\boldsymbol{B} = B_0 \left(\frac{y \hat{\boldsymbol{x}}}{L_y} + \frac{x \boldsymbol{y}}{L_x} \right), \tag{4}$$

$$82 E = -E_0 \hat{z} av{5}$$

where B_0 and E_0 are positive constants, L_x and L_y are the local characteristic lengths of B_y and B_x in the *x* and *y* directions, respectively. That is, the induction electric field remains uniform in this region, and the magnetic field increases with the distance away from the X line (or X point

- 86 in the (x, y) plane).
- 87 We first consider a general case of the motion of a test electron in the diffusion region.
- 88 Initially, the electron is at (x_0, y_0) and its velocity components are $v_{x0} > 0$, $v_{y0} > 0$, $v_{z0} > 0$.
- 89 The region considered is $2L \times 2L$. The fields and other parameters are illustrated in Figure 1.
- 90 The configuration here differs from that of Ref. 17, where the diffusion region is
- 91 one-dimensional. It is similar to that in Ref. 18, except that here more details are involved, such
- 92 that the FMR process can be better understood.



Figure 1. Schematics of magnetic field lines and electron trajectories in the 2D diffusion region. The X line in the *z* direction is at (0,0).

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97 An electron inside this box will be driven by the Lorentz and electric forces:

$$98 F_x = -qv_z B_0 x / L_x, (6)$$

99
$$F_y = qv_z B_0 y / L_y$$
, (7)

100
$$F_{z} = q(E_{0} + v_{x}B_{0}x / L_{x} - v_{y}B_{0}y / L_{y}), \qquad (8)$$

101 The trajectory of the electron is then given by

102
$$x(t) = x_0 + \int_0^t [v_{x0} - \int_0^{t'} \frac{q}{mL_x} v_z(t'') B_0 x(t'') dt''] dt'$$
(9)

103
$$y(t) = y_0 + \int_0^t [v_{y0} + \int_0^t \frac{q}{mL_y} v_z(t'') B_0 y(t'') dt''] dt'$$
(10)

104 where *m* is now the electron mass. The electron velocity is given by

105
$$v_x(t) = v_{x0} - \int_0^t \frac{q}{mL_x} v_z(t') B_0 x(t') dt', \qquad (11)$$

106
$$v_y(t) = v_{y0} + \int_0^t \frac{q}{mL_y} v_z(t') B_0 y(t') dt',$$
 (12)

107
$$v_{z}(t) = v_{z0} + \int_{0}^{t} \frac{q}{m} [E_{0} + v_{x}(t')B_{0}x(t') / L_{x} - v_{y}(t')B_{0}y(t') / L_{y}]dt'.$$
(13)

108 The initial and boundary conditions are $x(0) = x_0$, $x'(0) = v_{x0}$, $y(0) = y_0$, $y'(0) = v_{y0}$. Since 109 the transit time of the electron in the small diffusion region is very short [19], we can assume that 110 during the transient time the change δv_{z0} of v_{z0} satisfies $\delta v_{z0} \ll v_{z0}$ or $v_z(t')$ is constant in 111 Eqs. (9)-(12). As to be numerically verified in Section 4, the corresponding change in v_z is even 112 smaller. Eqs. (9)-(13) then yield

113
$$x(t) = x_0 \cosh(t / \tau_d) + v_{x0} \tau_d \sinh(t / \tau_d), \qquad (14)$$

114
$$y(t) = y_0 \cos(t/\tau_d) + v_{y0}\tau_d \sin(t/\tau_d),$$
 (15)

115
$$v_x(t) = x_0 \sinh(t/\tau_d)/\tau_d + v_{x0} \cosh(t/\tau_d),$$
 (16)

116
$$v_y(t) = -y_0 \sin(t/\tau_d)/\tau_d + v_{y0} \cos(t/\tau_d),$$
 (17)

117

$$v_{z}(t) = v_{z0} + \frac{q}{m} E_{0}t$$

$$-\frac{1}{2v_{z0}} [(v_{x0}^{2} + x_{0}^{2} / \tau_{d}^{2}) \sinh^{2}(t / \tau_{d}) + v_{x0}x_{0} \sinh(2t / \tau_{d}) / \tau_{d}]$$

$$+\frac{1}{2v_{z0}} [(v_{y0}^{2} - y_{0}^{2} / \tau_{d}^{2}) \sin^{2}(t / \tau_{d}) + v_{y0}y_{0} \sin(2t / \tau_{d}) / \tau_{d}],$$
(18)

118 where $\tau_d = \sqrt{\frac{mL_x}{qv_{z0}B_0}}$ is a characteristic time for electrons in the diffusion region. From Eqs. (14)

and (15), it is indicated that the electron oscillates in the *y* direction, but it is accelerated in the *x* direction. If we assume τ_1 to be the time when the electron leaves the box in the *x* direction, from Eq. (14) and $x(\tau_1) = L$ we get

122
$$\tau_1 = \tau_d \ln\left\{ \left[L + \sqrt{L^2 + v_{x0}^2 \tau_d^2 - x_0^2} \right] / (v_{x0} \tau_d + x_0) \right\}.$$
(19)

In order to see the acceleration process in more detail, we reasonably assume that thermal effects can be neglected. Thus, the initial in-plane velocity of an electron in the diffusion region is nearly zero. Considering the separation of the electron motion in the x and y direction, we only need to examine the electron motion in the x direction. With assumption $L = c / 2\omega_{pe}$, the transit time then becomes

128
$$\tau = \tau_d \ln \frac{c / 2\omega_{pe} + \sqrt{(c / 2\omega_{pe})^2 - x_0^2}}{x_0} .$$
 (20)

129 Since x_0 can be anywhere inside the box, the averaged transit time is

130
$$\overline{\tau} = \int_0^L \tau dx_0 / L = \frac{\pi}{2} \tau_d , \qquad (21)$$

131 so that the effective resistivity is given by

132
$$\eta_e = \frac{2}{\pi} \sqrt{\frac{m v_z B_0}{q^3 n^2 L_x}}$$
 (22)

133 If the particle is farther away from the X line, v_{x0} cannot be ignored, and the transit time is

134
$$\overline{\tau} = \frac{1}{L} \int_0^L \tau dx_0 = \tau_d \left[\tan^{-1} \frac{L}{\delta} + \frac{\delta}{L} \ln \frac{(L+\delta)\delta}{L^2 + \delta^2} \right] , \qquad (23)$$

135 where $\delta = v_{x0}\tau_d$. The corresponding effective resistivity is

136
$$\eta_{general} = \frac{m}{nq^2 \tau_d} \frac{1}{\tan^{-1} \frac{L}{\delta} + \frac{\delta}{L} \ln \frac{(L+\delta)\delta}{L^2 + \delta^2}}.$$
 (24)

137 Outside the region, δ is much larger (more precisely, v_{x0} is much larger and v_{z0} is smaller), 138 making effective resistivity much smaller there. Since v_{z0} is smaller outside the region, the 139 assumption $\delta v_z \ll v_{z0}$ may breakdown. That is, our interaction model is applicable only in the 140 small diffusion region around the X line.

141 If we include the ion motion, the current in Eq. (2) can be rewritten as

142
$$\boldsymbol{J}_{z\delta} = nq^2 \boldsymbol{E}_z(\boldsymbol{\tau}_e) / m_e \quad \boldsymbol{\tau}_i / m_i \quad .$$

143 where we have assumed that the plasma is quasi-neutral. Eq. (3) then becomes

144
$$\eta_{tot} = \frac{m_e m_i}{nq^2} \frac{1}{m_i \tau_e + m_e \tau_i}.$$
 (26)

145 Substituting Eq. (22), we get

(25)

146
$$\eta_{tot} = \eta_e \left(1 + \sqrt{\frac{m_e v_{ze}}{m_i v_{zi}}} \right)^{-1}$$
, (27)

147 where v_{ze} and v_{zi} are the local electron and ion velocities in the z direction.

148

149 **3. Simulation Model**

We have performed 2.5D PIC simulations for electrons on the (*x*, *y*) plane by assuming $\partial/\partial z = 0$. For convenience, we use the charge-conservation scheme (CCS) [20] instead of solving the Poisson equation, and the finite difference time domain method (FDTD) to solve the other Maxwell's equations. The particles are driven by the electric and Lorenz forces and the corresponding equations used in the PIC simulations are

155
$$\nabla \times \boldsymbol{E} = -\frac{\partial \boldsymbol{B}}{\partial t},$$
 (28)

156
$$\nabla \times \boldsymbol{B} = \varepsilon_0 \frac{\partial \boldsymbol{E}}{\partial t} + \mu_0 \boldsymbol{J} , \qquad (29)$$

157
$$\frac{d\boldsymbol{p}_j}{dt} = q_j (\boldsymbol{E} + \boldsymbol{v}_j \times \boldsymbol{B}), \qquad (30)$$

158 where *c* is the light speed, $J = n_i q_i V_i + n_e q_e V_e$, V_j (j = i, e) is the bulk velocity of species *j*, v_j 159 and $p_j = m_j v_j$ are the particle velocity and momentum, respectively. The variables are 160 normalized as follows: $x/d_{i0} \rightarrow x$, $(V_j, v_j)/v_{Ai0} \rightarrow (V_j, v_j)$, $\omega_{ci0}t \rightarrow t$, $B/B_0 \rightarrow B$, 161 $E/E_0 \rightarrow E$, $J/J_0 \rightarrow J$, $n/n_0 \rightarrow n$, $p_j/m_e v_{Ai0} \rightarrow p_j$, where $d_{i0} = c/\omega_{pi0} = c/\sqrt{n_0 q_i^2/\mu_0 m_i}$, 162 $v_{Ai0} = B_0/\sqrt{\mu_0 n_{i0} m_i}$, $\omega_{ci0} = q_i B_0/m_i$, $E_0 = v_{Ai0} B_0$, and $J_0 = n_0 q_0 v_{Ai0}$.

Our 2D simulation domain is $-D_x/2 \le x \le D_x/2$, $-D_y/2 \le y \le D_y/2$, where $D_x = 12.8d_{i0}$, $D_y = 6.4d_{i0}$, $dx = dy = 0.01d_{i0}$. Closed boundary condition is adopted in the *y* direction and periodic boundary condition is used in the *x* direction. The time step is $\omega_{ci0}\Delta t = 0.0002$, and the duration of the simulations is $\omega_{ci0}t = 40$, corresponding to 200,000 time steps. Nearly 82 million particles for each species are used in this simulation. We also assume $v_{Ai0}/c = 0.05$ and $\beta = 0.2$. The ion-to-electron mass ratio $M_{ie} = m_i/m_e$ is from 25 to 400, and the ion-to-electron initial

temperature ratio $T_{ie} = T_i / T_e = 5$. 169 We shall use the Harris equilibrium as the initial configuration. The initial magnetic field is 170 171 given by $B_x = B_0 \tanh(y/b_0), \quad B_y = B_z = 0,$ (31)172 173 and the initial density profile is $n = n_0 / \cosh(y / b_0)^2 + n_b$ 174 (32)where $B_0 = 1.0$, $b_0 = 0.5$, $n_0 = 1.0$, $n_b = 0.2$, and b_0 is the width of the current sheet with the 175 176 current intensity given by $I_{z} = B_{0} / b_{0} \cosh(y / b_{0})^{2}$. 177 (33)178 In order to shorten the initial stage in the simulation, we impose a small periodic excitation in 179 the initial system, such that Eq. (31) and (33) become $B_x = B_0 \tanh(y/b_0) + \varepsilon \pi \cos(2\pi x/D_x) \sin(\pi y/D_y)/D_y$ 180 (34) $B_{y} = -2\varepsilon\pi \sin(2\pi x / D_{x})\cos(\pi y / D_{y}) / D_{x}, \quad B_{z} = 0,$ 181 (35) $I_{z} = B_{0} / b_{0} \cosh(y / b_{0})^{2} + \varepsilon \pi^{2} \cos(2\pi x / D_{x}) \cos(\pi y / D_{y}) (1 / D_{y}^{2} + 4 / D_{x}^{2}),$ 182 (36)183 where $\varepsilon = 0.01$. Pressure balance yields 184 $P + \frac{B^2}{2} = (1+\beta)\frac{B_0^2}{2},$ 185 (37)where *P* and *B* are the local thermal pressure and magnetic field, $\beta = P / B^2$, and *P* and *B* are 186 normalized by $B_0^2 / 2\mu_0$. 187 188 4. Numerical Results and Comparison 189 190 First, we consider $M_{ie} = 25$, i.e., the same as that for the Geospace Environment Modeling (GEM) MR challenge [13]. Figure 2 shows the evolution of the induction electric field and 191

reconnected magnetic flux at the X line. We can see that MR occurs at t = 20-32, followed by a nonlinear stage of the process. Figure 3 shows the current J_z and the magnetic field lines at 194 different times. During the MR, the current sheet is compressed around the X line, and then 195 separated into two parts.

196 The electric field in the *z* direction as from the 2D electron fluid momentum equation is

197
$$E_{z} = -\frac{m_{e}}{e} \left[\frac{\partial V_{ez}}{\partial t} + V_{e} \cdot \nabla V_{ez} \right] - \frac{1}{n_{e}e} \left(\frac{\partial \Pi_{exz}}{\partial x} + \frac{\partial \Pi_{eyz}}{\partial y} \right) - \left(V_{e} \times \boldsymbol{B} \right)_{z},$$
(38)

198 where the pressure tensor is given by $\Pi_e = m_e \int (\mathbf{v} - \mathbf{V})(\mathbf{v} - \mathbf{V}) f_e(\mathbf{v}) d\mathbf{v}$, where $f_e(\mathbf{V})$ is the 199 electron velocity distribution function. Figure 4 shows the contribution of each term in Eq. (38) in 200 the current sheet when MR occurs. We see that the sum of the off-diagonal pressure tensors leads 201 to 80% of the induction electric field, similar to that found in Ref. 13.

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203

204 Figure 2 Evolution of reconnecting magnetic flux and the induction electric field on 205 the X line. Here ψ is normalized by $B_0 c / \omega_{pi0}$, and E_z is normalized by $B_0 v_{Ai0}$.



Figure 3 The distribution of the current density in the out of plane direction superposed with magnetic field lines at different simulation times.



Figure 4 Contribution of each term from Eq. (38) in the current sheet along the x direction (at y=0) at the peak reconnection time t=26.

215 In order to verify the assumption $\Delta v_z \ll v_{z0}$ used in Section 2, we compare the speeds of the

216 particles which are just before entering and after leaving the electron diffusion region. Figure 5 217 shows the distribution of electron velocity variation $f(\delta v_z)$ during t = 28 to 29 in the peaked MR period. Here, $\delta v_z = v_{z1} - v_{z0}$, where v_{z0} and v_{z1} are the electron velocity when it is just before 218 219 entering and after leaving the diffusion region, respectively. The mean of this distribution is 220 0.0470, and the variance is 0.2937. Electrons with $|\delta v_z/v_{z0}| \le 0.2$ constitute 78.33% of the total 221 ejected electrons, implying that most of the electrons suffer little change in the z-direction velocity. 222 In the earlier MR stage, such as from t = 18 to 19, the percent of electrons with $|\delta v_z/v_{z0}| \le 0.2$ is 90.96%. Thus, the velocity changes Δv_z for the majority of electrons are limited when they stay 223 224 in the smaller diffusion region, so that our assumption in the derivation of the effective resistivity 225 is justified. It is clearly also valid for ions, whose velocities are much less.





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Figure 5. Distribution of δv_{z} during t = 28 to 29.

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230 Figure 6 shows the time evolution of the average energy per electron for different components. "entering" and "leaving" means for electrons just before entering and after leaving 231 232 the electron diffusion region, respectively. We can see that the difference of the average energy 233 per electron in the in-plane component for the "entering" and "leaving" electrons is relatively 234 small at all times, which agrees with our assumption that the in-plane electric field is nearly zero 235 in Eq. (5). The energy gain of electrons in the z component increases with development of MR 236 during the period in the diffusion region. The energy gain is about 20% when MR reaches its 237 peak, which means the net change of the velocity in the z direction is about 10%. Therefore, it is further confirmed that our assumption $\Delta v_z \ll v_{z0}$ is valid. The energy gain of electrons 238

disappears after the fast reconnection stage ends. This behavior can be attributed to the fact that in the period of FMR, the induced electric field in the *z* direction is strong around the X line. On the other hand, the magnetic field is weak in this region and they are not sufficient to alter the trajectory of the hot electrons, which leads to electrons continuously accelerated in the *z* direction.

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244

245Figure 6. Time evolution of the average energy per electron for different246components. "entering" and "leaving" means for electrons just before247entering and after leaving the diffusion region, respectively.

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Figure 7 shows time evolutions of the effective resistivity in the electron diffusion region for different mass ratios M_{ie} . Since larger M_{ie} corresponds to a longer linear growth phase, we use larger initial excitation ($\varepsilon = 0.05$) for $M_{ie}=256$ and 400 to shorten simulation time. The other parameters remain the same. The theoretical η_e and η_{tot} , as well as the simulation result $\eta_s = E_z / J_z$, are all normalized by $B_0 / (n_0 q_0)$.

We can see that as MR enters into the fast reconnection phase, the effective resistivity exhibits quickly enhancement and the tendencies are almost the same for all the three effective resistivities. With increasing M_{ie} , not only do the peak values of the effective resistivity decrease, but also the difference between η_e and η_{tot} decreases, as can also be seen in Eq. (27). Since the PIC simulation involves larger noise level compared to the MHD simulation, the resistivity η_s directly from simulation fitting the modeled effective resistivity are reasonably well.

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- 261



Figure 7 Time evolutions of the effective resistivity from the model and PIC simulation for different M_{ie} 's. The time interval between the points is dt = 2.

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We also present the electric field E_z and the current density J_z in the z direction directly from the simulation in Figure 8. It is found that the changes of E_z and J_z are not in phase with the effective resistivity η_s . The effective resistivity further increases after the reconnection electric field E_z decreases. This is because the current density J_z always decreases and the decreasing speed is proportional to the electric field E_z , which is mainly attributed to the decrease of the electron density in the diffusion region.

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Figure 8 Time evolutions of the electric field and the current density in the z direction for different M_{ie} 's. The time interval between the points is dt = 2.

276

277 The inertial conductivity σ_i from Eq. (14) of Ref. [17] is

278
$$\sigma_i = \frac{ne^2}{m}\tau = \frac{ne^2}{m}\frac{L}{v} = \left(\frac{Ln^2e^3}{2mE}\right)^{1/2},$$
(39)

where *L* is the length of the accelerating region, *v* is the particle velocity and *E* is the electric field [17]. Here *m* we take as the electron mass. It is evident that this model is not able to implement into MHD because we first have to know the resistivity to calculate the electric field. Another problem is that the estimated resistivity from this model is about 5 times larger than the numerical results from $\eta_s = E_z / J_z$.

284 Summary

This paper introduces a simple model for energy conversion in FMR. Using the simple equation $E = \eta J$, we define a space-time dependent effective resistivity η that can be obtained from numerical solutions of test electron trajectories in the diffusion region. We find that η rises with development of MR, reaching its maximum when MR reaches its peak. It then falls and finally reaches a low value. The results from the model agree fairly well with that from the PIC simulations. It is also found that with the increase of M_{ie} , the peak value of effective resistivity tends to be smaller.

We wish this paper can give a new view on anomalous resistivity in MHD simulation, whose idea is derived from a collisionless fast reconnection model, and the physical meaning is reasonable.

295 Acknowledgements

We thank Prof. M. Y. Yu for many useful advices and polishing on this paper, and also thank H.
W. Zhang for many useful discussions. This work is supported by the National Natural Science
Foundation of China under Grant No. 41474123, National Magnetic Confinement Fusion
Science Program of China under Grant No. 2013GB104004 and 2013GB111004, the Special
Project on High-performance Computing under the National Key R&D Program of China No.
2016YFB0200603, Fundamental Research Fund for Chinese Central Universities.

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