

A Scheme for Reconstructing Diagnostic Data Based on Compressed Sensing Theory¹

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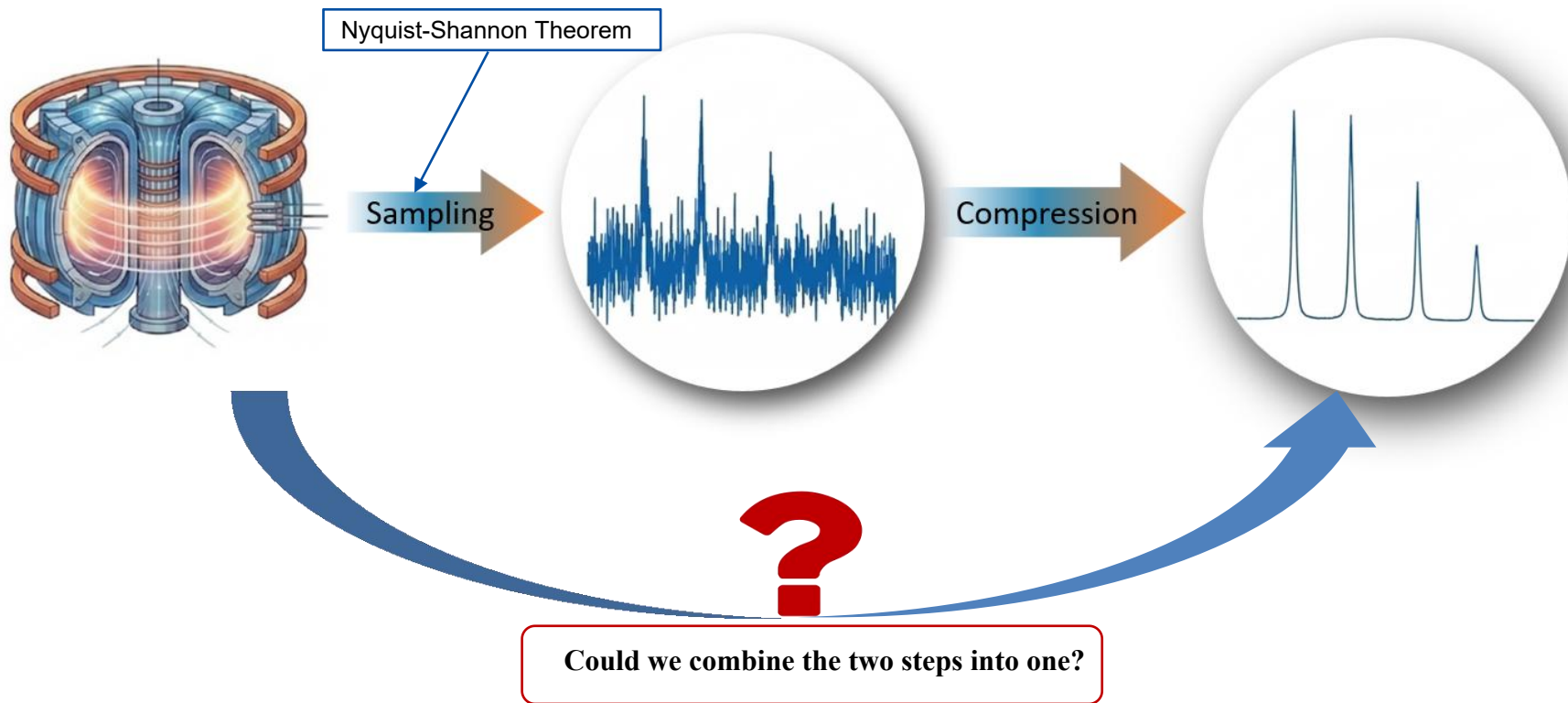
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01

Background



Compressed Sensing is a signal processing theory that breaks the Nyquist-Shannon theorem by **leveraging sparsity to enable perfect reconstruction of the original signal** [Donoho, IEEE Trans. IT, 2006; Candes, Romberg & Tao, IEEE Trans. IT, 2006]. It is **interpretable**.

Sparsity:

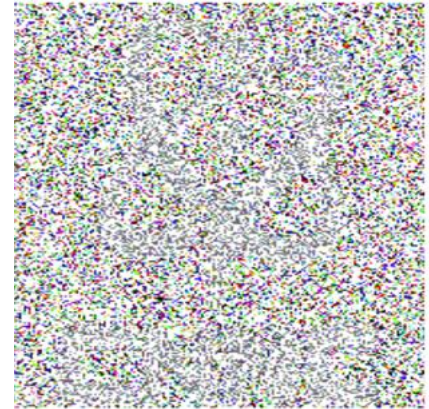
- Signal is sparse in a transform domain;
- Only a few coefficients are non-zero.

Incoherent measurements:

- Measurement matrix is incoherent with the sparse basis;
- Each measurement captures global information;
- Example: random Gaussian/Fourier matrix.

Optimization-based reconstruction:

- Sparsest solution is recovered from an optimization problem;
- L_0 -norm minimization: **nonconvex optimization problem, NP-hard**;
- L_1 -norm minimization: **convex optimization problem, solvable, but high per-iteration cost and numerous iterations emerge for high-dimensional signals**.

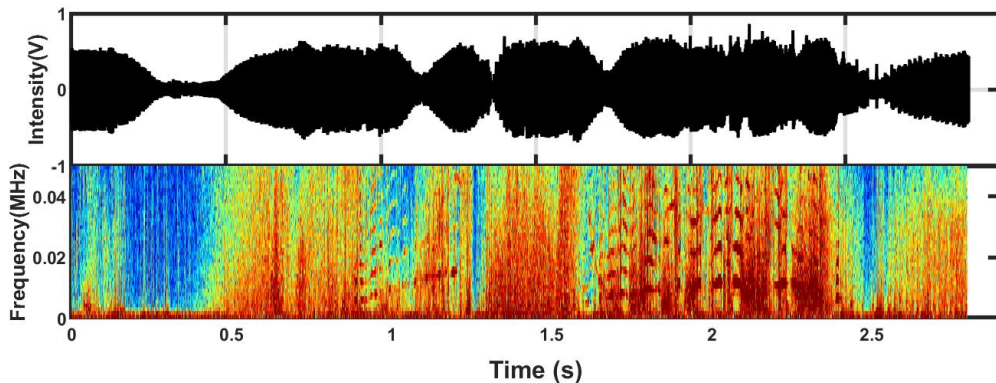


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Method

Plasma signals are heterogeneous.

- Localized gradients
- Smooth background
- Non-differentiable perturbations



Single transform basis is insufficient. Different signal structures demand distinct representation domains.

- To address this, we propose an **adaptive, data-driven multi-domain sparse representation**:

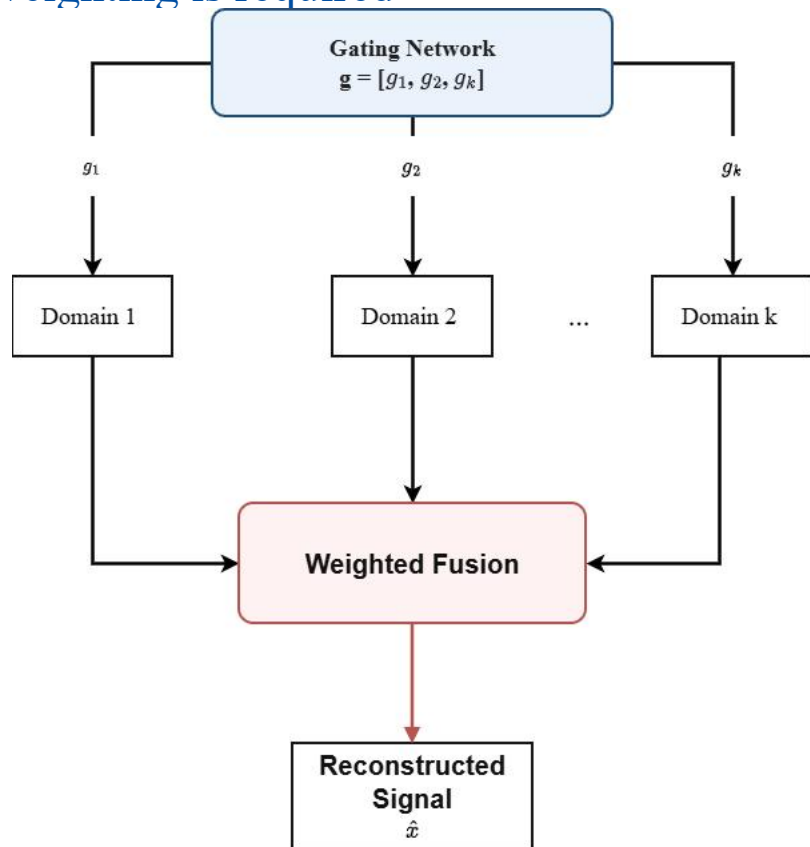
$$\mathbf{x} = \sum_{k=1}^K \mathbf{D}_k \alpha_k$$

Different domains contribute differently → adaptive weighting is required

Adaptive, data driven weighted combination of multiple domains [Wu, et al, ICLR, 2020]:

$$\mathbf{x} = \sum_{k=1}^K g_k \mathbf{D}_k \boldsymbol{\alpha}_k$$

- Different domains capture different structures
- **Dynamic combination**
- Gating network



Classical compressed sensing:

- **Model-driven algorithm**
- Convex optimization problem

$$\min_{\alpha} \|y - A\Psi\alpha\|_2^2 + \lambda\|\alpha\|_1$$

- Solved by iterative algorithms

sparsity

$$x^{k+1} = S_{\lambda}(x^k - \eta A^T(Ax^k - y))$$

- Numerous iterations
- High computational cost
- Slow convergence

map iterations to layers

Deep Unfolding

fidelity

We introduce the **deep unfolding algorithm** [Gregor & LeCun, ICML, 2010] that bridges model-based and data-driven methods.

Layer 1

Layer 2

Layer 3

...

Layer k

- The optimization problem is formulated as:

$$\min_{\alpha} \frac{1}{2} \|y - A\Psi_{eff}\alpha\|_2^2 + \lambda \|\alpha\|_1$$

- y : observed signal
 - A : measurement matrix
 - Ψ_{eff} : adaptive multi-domain dictionary
 - α : sparse coefficients
- This problem is typically solved using iterative shrinkage algorithms.

$$\alpha^{(t+1)} = S_{\lambda}(\alpha^{(t)} + \eta\Psi_{eff}^T A^T (y - A\Psi_{eff}\alpha^{(t)}))$$

- Gradient step: reduces data fidelity error
- Shrinkage operator S_{λ} : enforces sparsity

Each iteration = Linear transform + Nonlinear shrinkage

Classical iteration:

$$\alpha^{(t+1)} = S_{\lambda}((I - \eta\Psi^T A^T A\Psi)\alpha^{(t)} + \eta\Psi^T A^T y)$$

- Repeated matrix multiplications
- Slow convergence
- Fixed operator



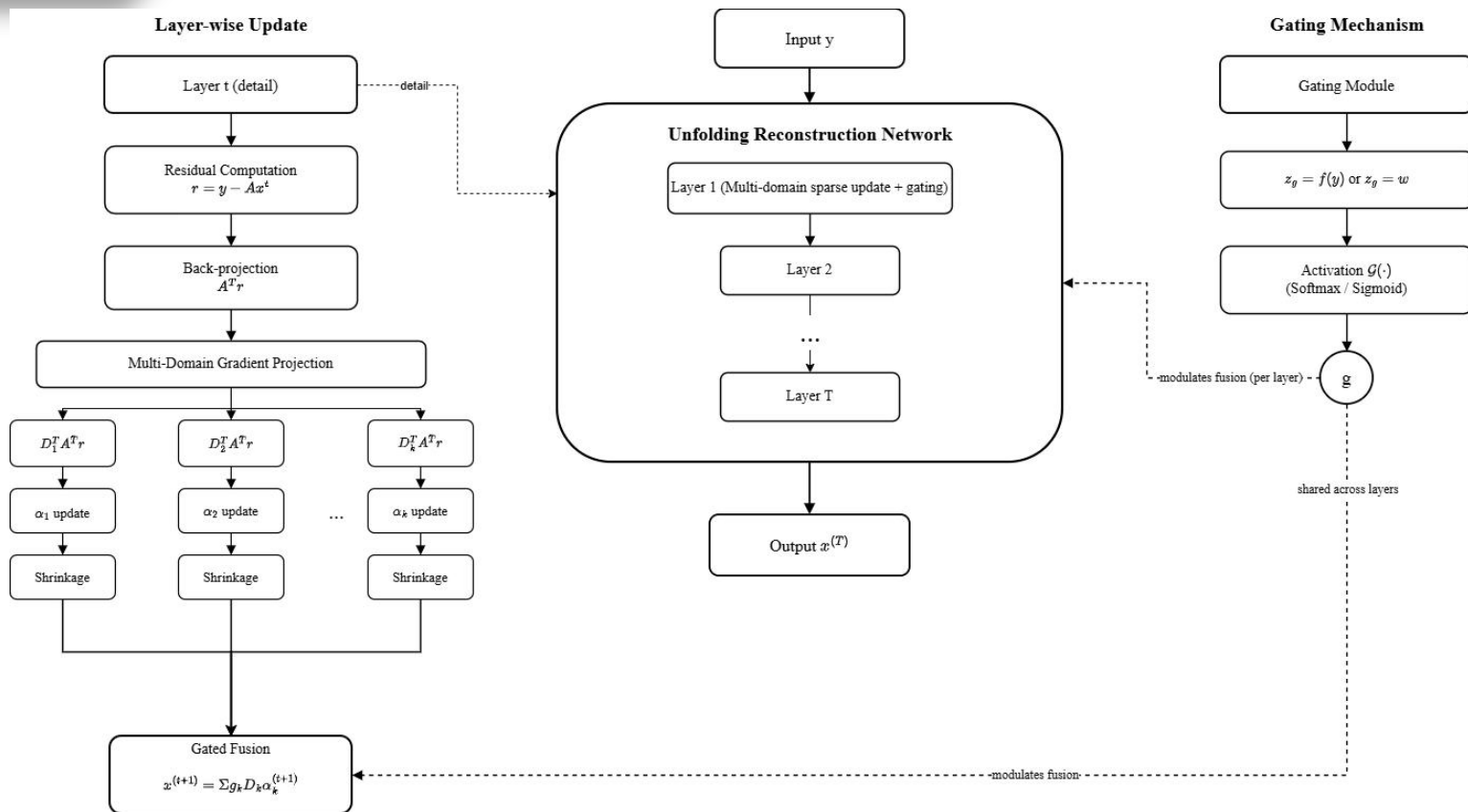
• Deep unfolding:

$$\alpha^{(t+1)} = S_{\theta^{(t)}}(W^{(t)}\alpha^{(t)} + b^{(t)})$$

- No explicit matrix construction
- Fixed-depth feed-forward
- Learnable operators

- Replace iterative matrix operations with learnable operators
- Efficient inference while preserving optimization structure

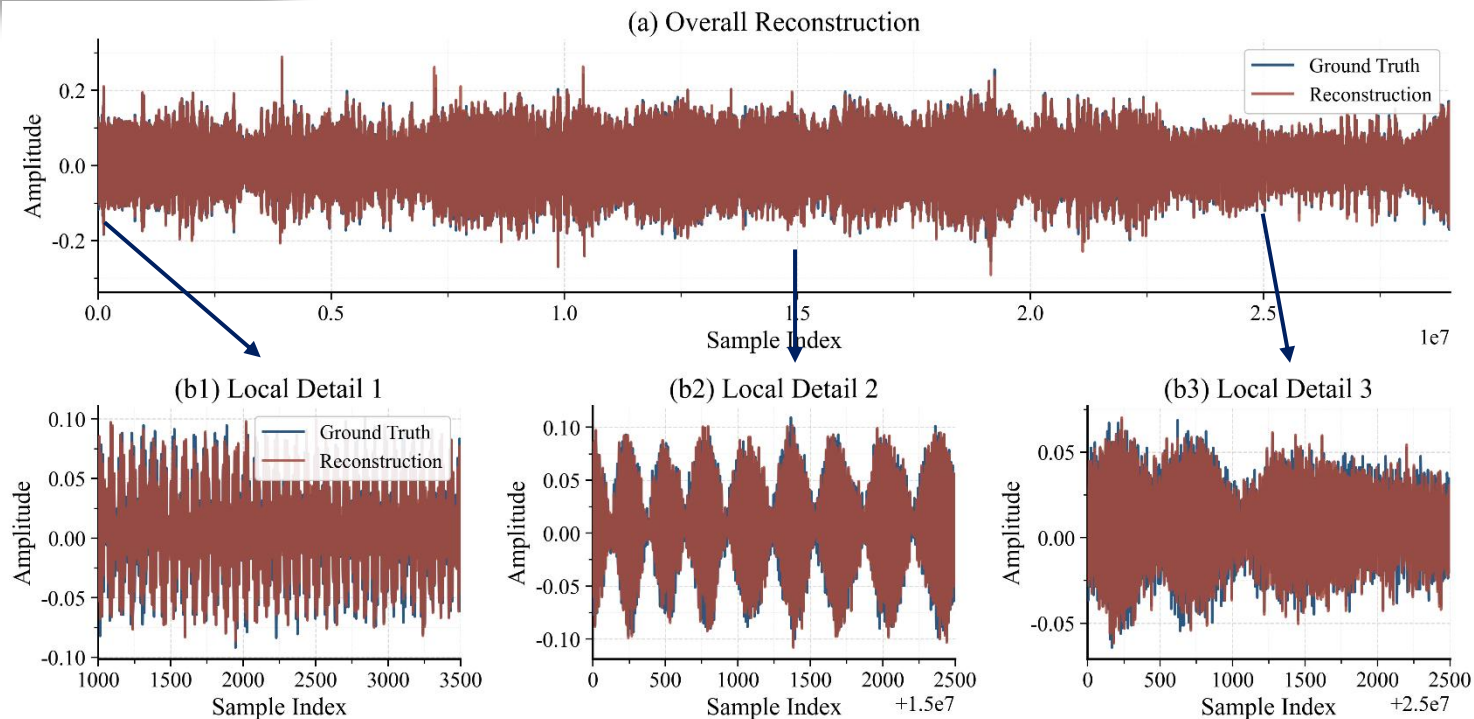
interpretability of compressed sensing theory + computational efficiency of deep unfolding



Multi-domain representation + adaptive gating + deep unfolding

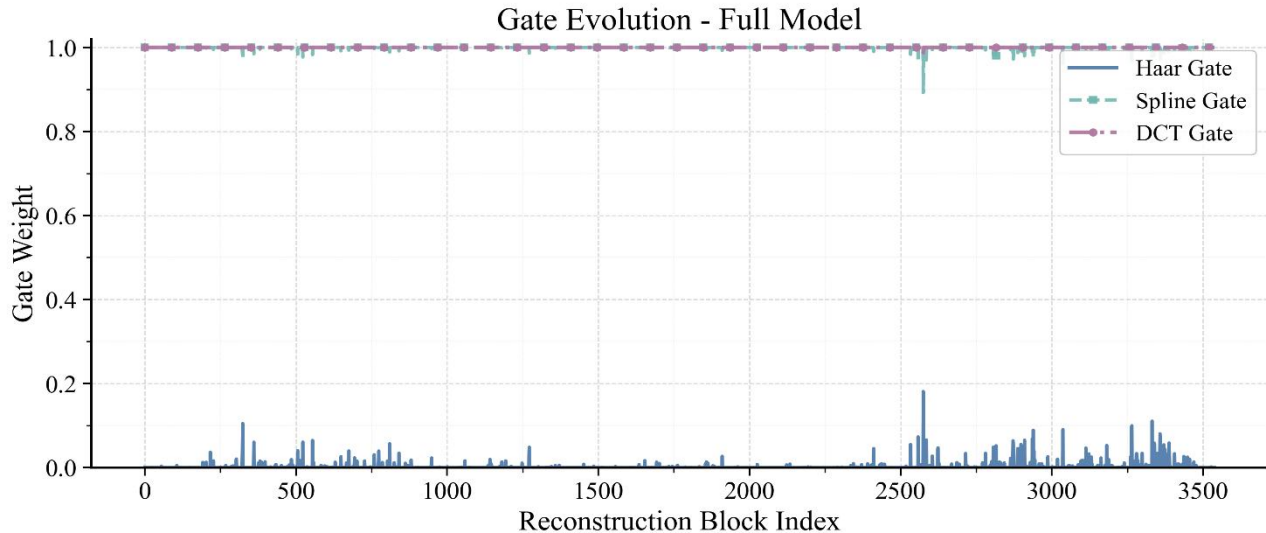
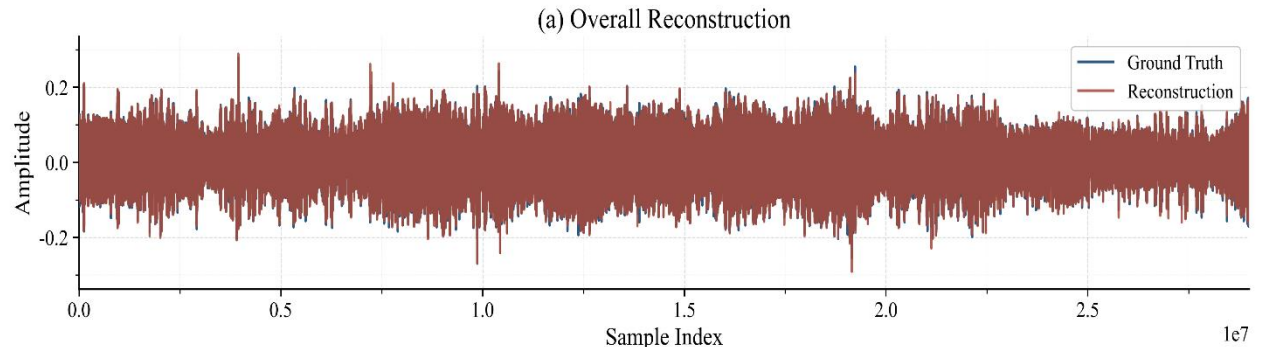
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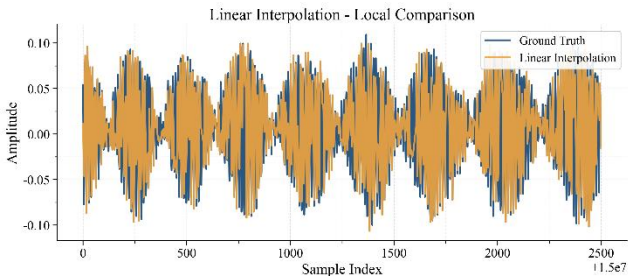
Results



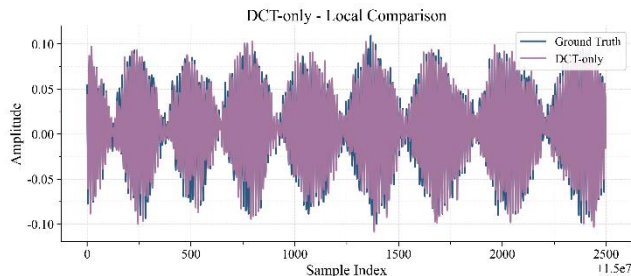
- High-fidelity reconstruction under severe undersampling (40% completeness)
- Global consistency: Reconstruction are consistent with ground truth

- Adaptive domain selection via gating mechanism
- Dominant contribution from smooth basis (DCT)
- Sparse activation of Haar/Spline for local structures
- Enables multi-scale representation of heterogeneous signals

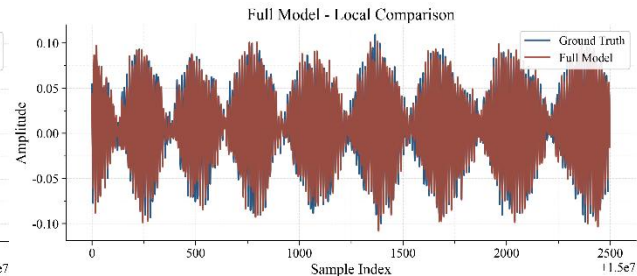




Linear Interpolation



DCT-Only



Full Model

Comparison for data with only 40% completeness

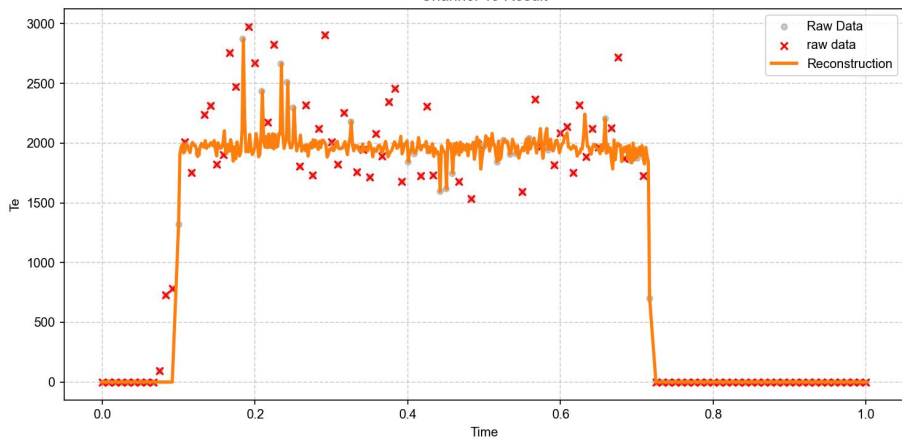
RMSE: Root Mean Square Error
NMSE: Normalized Mean Square Error
SSIM: Structural Similarity Index Measure

Model	RMSE ↓	NMSE ↓	SSIM ↑
Linear Interpolation	0.022	0.285	69.7%
DCT-only (No Gate)	0.011	0.066	92.8%
Full Model	0.006	0.023	93.4%

Compared with linear interpolation: RMSE reduced by ~73% SSIM improved by ~23%

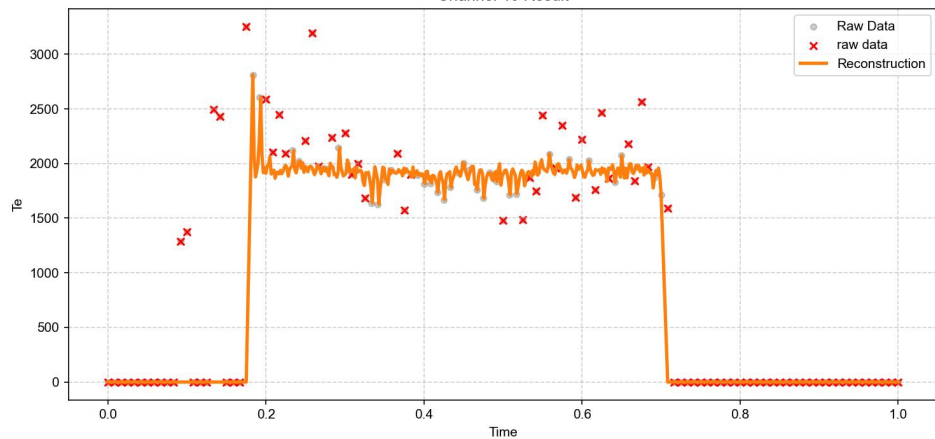
Building on the signal reconstruction framework, we further apply it to enhance the temporal resolution of Thomson Scattering.

Channel 45 Result



Channel 45

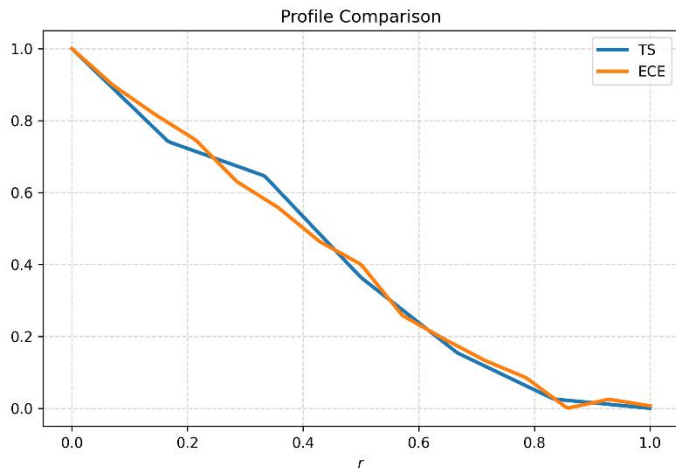
Channel 46 Result



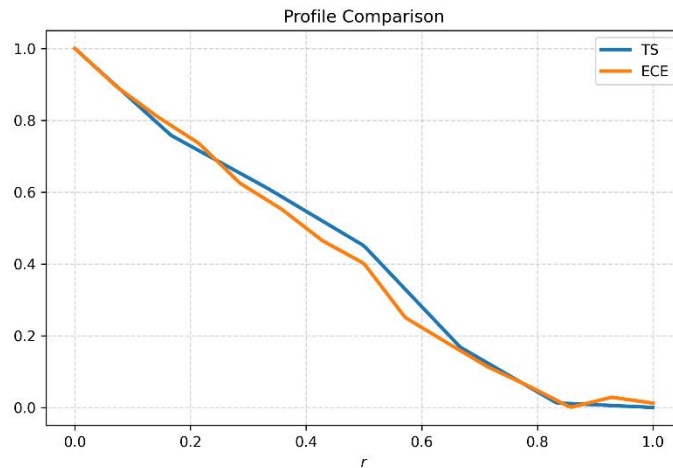
Channel 46

Temporal resolution enhanced from 121 to 633 sampling points, enabling reconstruction of fine dynamic features.

To verify the validity of Thomson scattering temporal super-resolution, the **reconstructed results** were compared with ECE cross-sectional images.



1114ms



785ms

Reconstructed TS profiles show good agreement with ECE measurements, verifying the physical consistency.

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Discussions

We propose an effective data reconstruction framework based on the compressed sensing theory.

- For the first time, we integrate compressed sensing theory with a deep unfolding–based gated multi-domain sparse representation framework, establishing a structured and interpretable reconstruction paradigm.
- A joint dictionary is introduced to capture heterogeneous structures in plasma diagnostic signals, including smooth backgrounds and localized variations.
- The model effectively combines interpretability (model-driven) with flexibility (data-driven), achieving a balance between physical consistency and learning capability.
- It exhibits strong performance in reconstructing incomplete data under realistic acquisition constraints.

- **Overall Loss:**

$$L = \|\mathbf{x}_{rec} - \mathbf{x}_{true}\|_2^2 + \lambda_1 L_{SSIM} + \lambda_2 \|z\|_1 + \lambda_3 \|g\|_1$$

- **Each Term Explanation**

$\|\mathbf{x}_{rec} - \mathbf{x}_{true}\|_2^2 \rightarrow$ reconstruction accuracy

$L_{SSIM} \rightarrow$ structure preservation

z sparsity \rightarrow multi-domain prior

g regularization \rightarrow stabilize gating

Evaluation Metrics:

- RMSE:

$$RMSE = \sqrt{\frac{1}{N} \sum (x_{rec} - x_{true})^2}$$

sensitive to large deviations

- NMSE:

$$NMSE = \frac{\sum (x_{rec} - x_{true})^2}{\sum x_{true}^2}$$

removes scale dependency

- SSIM:

$$SSIM(x, y) = \frac{(2\mu_x \mu_y + C_1)(2\sigma_{xy} + C_2)}{(\mu_x^2 + \mu_y^2 + C_1)(\sigma_x^2 + \sigma_y^2 + C_2)}$$

evaluates structural similarity;
sensitive to local patterns and edges

RMSE/NMSE \rightarrow error, SSIM \rightarrow structure